

# Enabling Reconfiguration of Component-Based Systems at Runtime

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## 1 Introduction

The development of software systems iterates over analysis, design, implementation, and deployment. Subsequent iterations require refactoring [2] of design and reconfiguration of deployed systems. At least three software engineering disciplines are involved when dealing with runtime reconfiguration of component-based software systems:

- software architecture,
- software configuration management, and
- software component deployment

These disciplines contribute in various ways. Software architectures play a central role at design, describing a system model and specifying it in a formal way using some architecture description language [7]. Configuration management focuses on implementation, defining a configuration from various component versions and building a system from this configuration [6]. Component deployment addresses the deployment phase, managing all dependencies among the involved components and eventually producing a running system [1, 12].

Although these three activities may evolve independently and provide their own models of the system, they are all involved when reconfiguration is required (roundtrip engineering). Applying planned changes to a deployed system usually triggers changes in all those system models to obtain a consistent system after reconfiguration. A major problem to be solved here is managing (run-time) dependencies among the components. Therefore, we need a formal system model, which covers components, their interconnection, communication, and run-time behavior, integrating all the system models of software architecture, configuration management and component deployment [13].

## 2 An Approach to Enabling Reconfiguration of Component-Based Systems at Runtime

We aim at Reconfiguration of Component-Based Systems at Runtime. Our proposed approach employs:

- Parameterised Contracts [8] as a method for formal component specification, adding a formal run-time component description technique,
- using graphs [5] to describe dependencies among components and considering run-time concerns,
- extending C2-ADL [11] with a concept of containers to establish modelling of a deployment and runtime properties of a system,

This combination shall be the way to provide a foundation for achieving our goals. Figure 1 displays our suggested system configuration. A system configuration is designed as a hierarchy using three GoF design patterns [3]: *composite*, *decorator* and *adapter*.

- Composite is required to build a system configuration,
- The Decorator pattern allows functional changes to components,
- The Adapter pattern (wrapper) allows changes of their interfaces

Furthermore the concept of containers allows us to manage the process of run-time reconfiguration as *run-time re-deployment* of components.

Our Reconfiguration Manager (a special type of connector) is activated on every *reconfiguration request*. It consists of:

- Reconfiguration Analyzer
- Dependency Manager
- Consistency Manager
- Reconfigurator

The Reconfiguration Analyzer takes a *reconfiguration request*, analyzes and classifies the requested change. Our Dependency Manager monitors the run-time dependencies among components, determines a minimal set of change-affected components and sends a *change request* for each

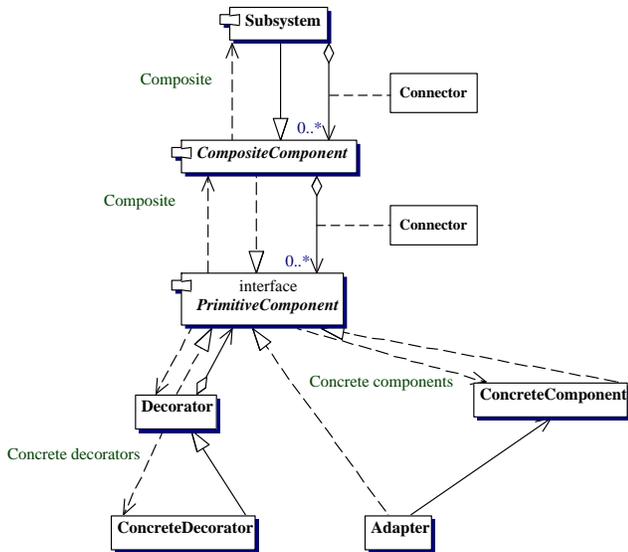


Figure 1. System Configuration

involved component to the reconfigurator. The Consistency Manager controls the system. We divide its activities into:

- Pre-Reconfiguration: checking the static consistency of the intended system configuration and moving a consistent system into a *ready-to-configure-state*, or refusing the reconfiguration request on failure.
- Post-Reconfiguration: checking the (run-time) consistency of a changed system and, on success, confirming a reconfiguration, or sending a *rollback request* to the reconfigurator.

The Reconfigurator realizes the reconfiguration as a dependent change transaction [4]. It starts a transaction, transfers all affected components into a *blocked* state, isolates an affected subsystem, applies the changes, and sends a *consistency-check-request* to the consistency manager. On success it commits the transaction, on failure it initiates a rollback and transfers the changed or unchanged system into a running state.

Figure 2 displays all states a component can take at system runtime. Just after it has been deployed we assume that it is *free*. We distinguish between the states *busy*, which means *is in use* and *active*, which means *is executed*. Therefore, a component can't directly move into a state *active & busy*. Only free components can be transferred into a *blocked* state and be changed afterwards. This means, our reconfiguration takes place while the system is running, we are not trying to achieve an ad-hoc component change.

We assume that a (sub)system can take only four states at runtime: *running*, *ready to configure*, *reconfiguring* and *restoring* (Figure 3). For each state a corresponding part of

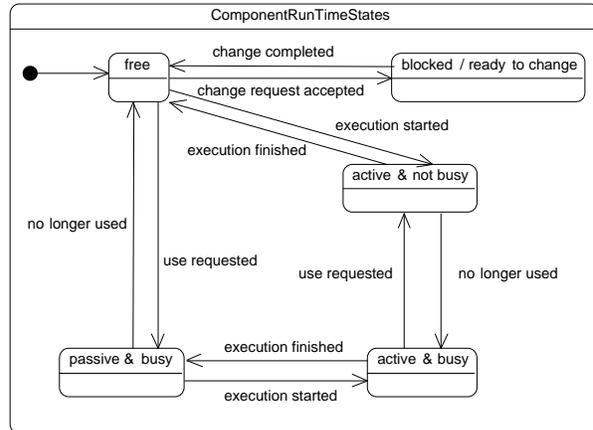


Figure 2. Component Run Time States

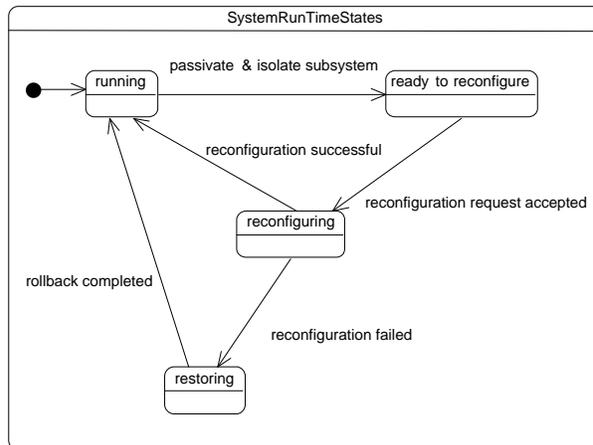


Figure 3. System Run Time States

the reconfiguration manager initiates and controls possible changes from one state into another.

### 3 Summary

We present an approach to enabling reconfiguration of component-based systems at runtime. This approach combines the disciplines software architecture, configuration management and component deployment.

As an implementation platform we are using J2EE-Technology [10]. We are intending to extend its Specification of the deployment process with a subprocess of *re-configuration* [9]. Currently, we are investigating the possibilities to control or manipulate the deployment process at different application servers and develop a methodology for determining and formally specifying dependencies among already deployed components.

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