

## On the *in situ* measurement of temperature and electrical conductivity of sea-water

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**Abstract**—After some brief comments on the measurement of temperature and electrical conductivity in oceanography, the measuring probes suitable for *in situ* measurements are reviewed. Then the method of measurement is described using an improved model of the so-called bathysonde. This makes possible a continuous recording of temperature, conductivity, and pressure with high accuracy in great depths. Measurements from the Skagerrak and from the Mediterranean are considered. Finally, problems are discussed which arise when evaluating electrical conductivity and temperature from *in situ* measurements.

### INTRODUCTION

ONE of the most important problems in physical oceanography is the determination of density and sound velocity in sea water. Indirect methods use the values for temperature and salinity—the latter being derived from the chlorinity—or the values for temperature and electrical conductivity. Recent investigations by COX *et al.* (1962) have shown that a greater accuracy in the density determination is achieved with conductivity than with chlorinity measurements. By accident, because of the technical possibility of measuring temperature and conductivity *in situ*, several institutes have been using these two parameters for density determination for a number of years. Depending on the different requirements of the particular oceanographic problem to be solved and of the sea area to be surveyed different types of instruments have been developed. The general aim is a device which, by the use of telemetering techniques, simultaneously with *in situ* measurements, records, and possibly even evaluates the data on shipboard or in a laboratory ashore.

As telemetering *in situ* temperature measurements always implies transforming the measured values into electrical signals an electrical thermometer is usually used. An exception is the technique used by JOSEPH (1962) with the 'Delphin' where the movement of a capillary tube spring, filled with a temperature sensitive liquid, was transformed by mechanical scanning into a variation of the time interval between electrical impulses.

The usual measuring probes are metal resistance thermometers, thermistors, and thermoelements. The thermoelements are only used in those cases where a fast time response with a good relative, but less absolute, accuracy is required (KALLE, 1942; 1953), but generally a high absolute accuracy is needed to detect long-term variations in the structure of water masses. For this reason metal resistance thermometers and thermistors are preferred. Quite often thermistors are chosen for continuous recordings because, due to their high temperature dependence, they can easily be used in electrical circuits (ANDERSON and BURKE, 1951; MORTIMER and MOORE, 1953; DORRESTEIN 1954; HAMON 1955; PRITCHARD 1959; GERMAN 1960; WILLIAMS 1961; BOOKER 1961). One disadvantage is the insufficient constancy of the resistance value of the thermistor, so that measurements with an accuracy of more than about  $\pm 0.05^{\circ}\text{C}$  can be achieved only with frequent calibration tests. If good constant readings are wanted over a long period, the best method is to use a platinum resistance element (HINKELMANN, 1956; 1957) as in the so-called bathysonde. It is possible to obtain the very small thermal time constant of 0.16 sec with a special design. The disadvantage when compared with the thermistor is the small temperature coefficient of the platinum wire, which therefore requires a more sensitive electrical circuit.

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There are three methods of measuring electrical conductivity, each distinguished by the manner of coupling the solution to the measuring circuit: The electrode, the capacitive, and the inductive method. Capacitive coupling with high frequency is only known in measurements in the laboratory (HUEBNER, 1959) whereas coupling with electrodes was the most usual procedure at first with *in situ* measurements (JACOBSON, 1948; DORRESTEIN, 1954; HAMON, 1955; ESTERSON, 1957; SCHIEMER and PRITCHARD, 1957). One advantage is the direct transformation of the conductivity of the sea-water into a measurable resistance; the most important disadvantage is the dependence of the measurement on the condition of the electrode surface. Electrode assemblies may be used with *in situ* measurements up to an absolute accuracy of about  $0.1 \cdot 10^{-3} \Omega^{-1} \text{ cm}^{-1}$ . For a higher accuracy over a longer period the contamination of the electrodes is so great in the open sea that only the inductive method can be used. It has been used for this purpose by ESTERSON (1957), HINKELMANN (1958), PRITCHARD (1959), GERMAN (1960), WILLIAMS (1961) and BROWN (1961).

The author has worked since 1958 with several types of bathysonde (HINKELMANN, 1956, 1957, 1958; KROEBEL, 1961) in different sea areas (SIEDLER, 1961). As we have now obtained successful measurements of temperature and electrical conductivity even from great depths, it seems desirable to describe the present state of the technical development of this device and to discuss the problems arising in the evaluation of its records.

In order to obtain a direct record of temperature and electrical conductivity as a function of depth, the device in addition to the temperature and conductivity probes has a Bourdon tube to measure the hydrostatic pressure. The three measuring probes for temperature, conductivity and pressure are frequency-determining parts of three oscillator circuits which work respectively within the ranges 0.86 to 1.5 kc/s; 2.57 to 4.5 kc/s and 6 to 9 kc/s. To avoid the use of multiconductor cables, as their weight requires a big winch for work at great depths, an especially developed single conductor cable was used to carry the underwater unit (SIEDLER, 1962) with the current returning to the ship through the sea water. The frequency signals are transmitted back to the ship over the single conductor cable and are either recorded on a magnetic tape recorder or transformed into d.c.-current. Thus, the dependence of the temperature and conductivity on the pressure, i.e., on the depth, can then be recorded on a double-function X-Y-recorder. In order to use the instrument in any oceanic area the following ranges and accuracies were required :

temperature :  $-2$  to  $+35^\circ\text{C}$ ;  $\pm 0.02^\circ\text{C}$

electrical conductivity :  $20$  to  $70 \cdot 10^{-3} \Omega^{-1} \text{ cm}^{-1}$ ;  $\pm 0.02 \cdot 10^{-3} \Omega^{-1} \text{ cm}^{-1}$ .

This means that for  $10^\circ\text{C}$  and a salinity of 35‰ there is an accuracy of  $\pm 0.04\%$ . If all frequency determining components of the oscillators which are temperature sensitive are installed in a thermostat, the frequency error of the oscillators is less than 1 per cent of the frequency range. To achieve the accuracy of  $\pm 0.02^\circ\text{C}$  and  $\pm 0.02 \cdot 10^{-3} \Omega^{-1} \text{ cm}^{-1}$ , the range had to be subdivided. This subdivision can be made (1), in the oscillators and (2), before or (3), after the frequency measurement in the shipboard portion of the instrument. The first provides the greatest and the third the least increase in accuracy. Frequency signals are used to make the switch in the oscillators by remote control when lowering the underwater unit. As this requires some technical care only as many steps for subdividing the range are made in the underwater device as are really necessary; others can be made on shipboard before the frequency measurement. The Kieler Howaldtswerke constructed an instrument (Fig. 1) according to specifications provided by the Institut für Meereskunde, Kiel. The underwater unit had 10 switch positions each, for temperature and conductivity. Position 1 covered the whole range ( $-2$  to  $+35^\circ\text{C}$ ;  $20$  to  $70 \cdot 10^{-3} \Omega^{-1} \text{ cm}^{-1}$ ), positions 2 to 9 overlapping sub-ranges. The changeover was made on shipboard by switching the transmitter to combinations of the five frequency signals of 10.5–12.0–13.7–15.6–17.8 kc/s. The pressure oscillator was not switched because hysteresis and the temperature dependence of the Bourdon tube limited the accuracy of the pressure reading to about 1 per cent. The three frequencies for temperature, conductivity, and pressure are separated on board with filters. To achieve a high relative frequency shift  $(f_2 - f_1)/f_1$ , the following method is used : The frequency of the temperature oscillator (0.86 to 1.5 kc/s) is multiplied by 3 to get the same range as the conductivity oscillator (2.57 to 4.5 kc/s). Using five overlapping sub-ranges (2429–2945; 2842–3358; 3255–3771; 3668–4184; 4081–4597 c/s) the two frequencies for temperature and conductivity are heterodyned to the range 363 to 879 c/s. After transformation of the resultant frequencies into d.c. current the measured values are recorded on a double-function X-Y recorder. The original frequencies may, however, also be fed directly into a digital computer.

The first tests, thanks to the kind assistance of the Oceanografiska Institutet, Göteborg, could be carried out in the Gulmarfjord. These tests and the first measurements of the thermohaline layering with this instrument in the Skagerrak and Kattegat on board the research cutter *Hermann Wattenberg*,

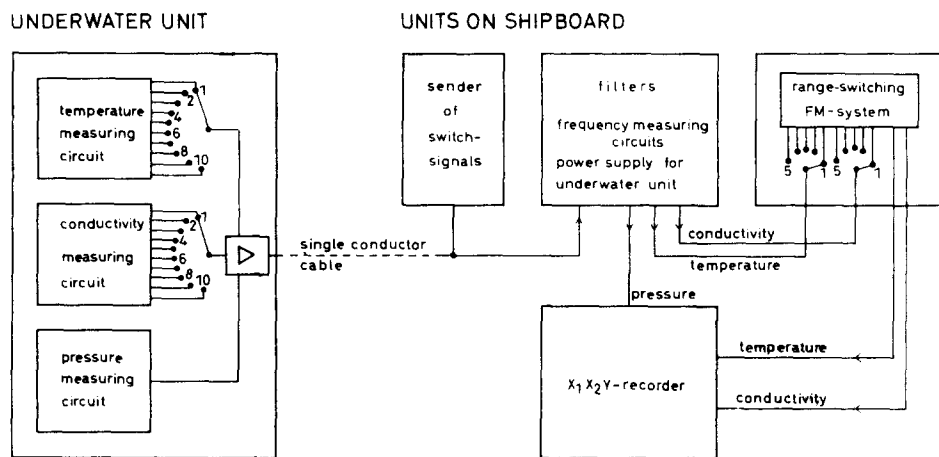


FIG. 1. Block diagram of the bathysonde.

Kiel University, proved the usefulness of the method. FIG. 2 is an example of the temperature record in the Skagerrak. On the left is shown the record with a large range (1/2 means switch-position 1 for the whole range in the underwater unit and switch-position 2 for the second sub-range in the shipborne unit), and on the right the record made on the next lowering with several sub-ranges from the same locality. Naturally, in an area with such a strongly variable layering the less accurate but more conspicuous measurement will generally be preferred. The first measurements in the deep-sea in the Mediterranean could be made, thanks to the Bureau d'Études Océanographiques, Toulon, on board the French research ship *Origny*. The maximum depth (2000 m) was not reached because the cable used only allowed measurements down to 1600 m depth.

FIG. 3 is an example of the record of temperature and conductivity. As the variations with depth are very large in the upper 50 m, the large range 1/3 was used for the temperature and for the conductivity. To get an idea of the fine structure of the layering in greater depths one small range was used from 50 to 1600 m. Thus records were obtained with optimum adaptation to existing conditions. FIG. 4 compares temperatures measured on lowering and on raising the bathysonde. Great differences are apparent in the temperature layers between measurements made within a half hour at nearly the same place even in the deep sea (Station No. 27, 43° 28'N, 7° 28'E, 18 May 1962).

All measurements with the bathysonde were compared with those obtained with reversing thermometers and Nansen-bottles. These were evaluated by the author at the Institut für Meereskunde, Kiel University. Those obtained in the Mediterranean were also evaluated by PELUCHON, Bureau d'Études Océanographiques, Toulon, and by HINKELMANN, Institute for Applied Physics, Kiel University. Since the measurements with the bathysonde and the Nansen-bottles were not made at exactly the same time, they were not absolutely identical because of the slight drifting of the ship and due to fluctuations in the temperature layers in the interval between the two types of observation. Furthermore, it was impossible to decide whether the two measurements to be compared came from exactly the same depth because the Nansen-bottle depth was determined on the one hand by the wire length together with the wire angle at the sea surface and on the other hand the bathysonde depth was based on the pressure record. In the upper 500 m, however, differences of about 20 m have a marked effect on the errors incurred. Considering the sources of these errors, one may conclude from the records already on file that the deviation of the temperature recorded with the bathysonde

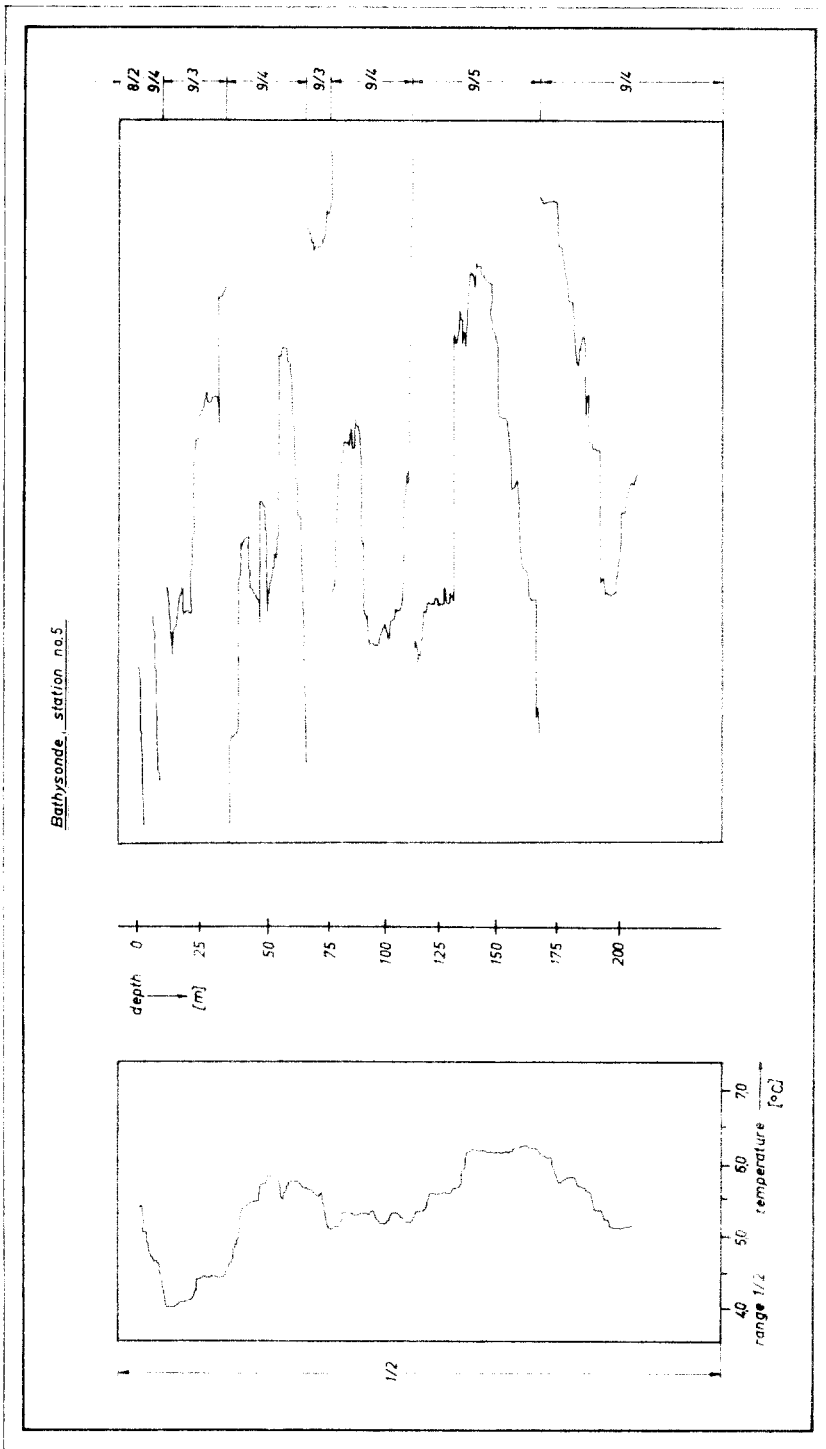


FIG. 2. Temperature record in the Skagerrak.

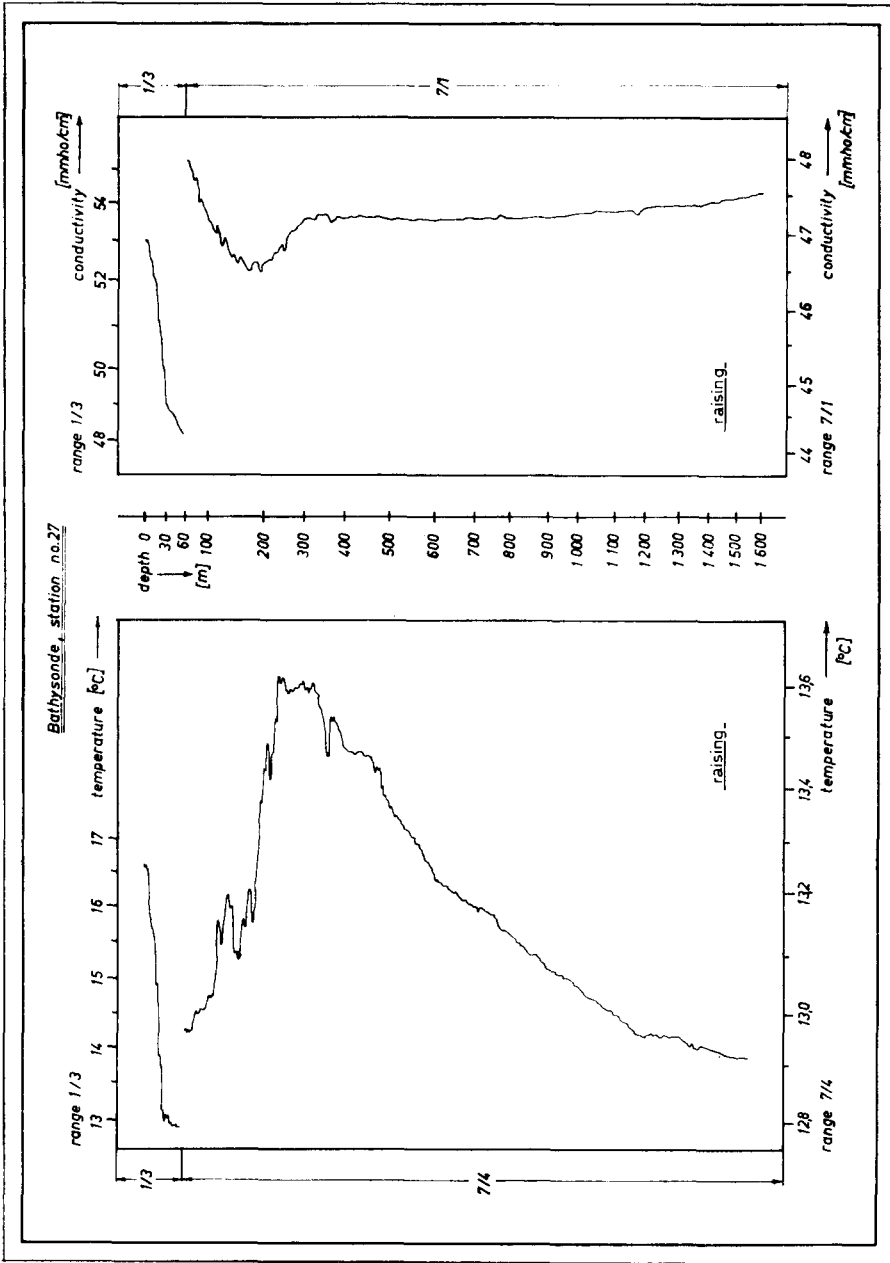


FIG. 3. Temperature and conductivity record in the Mediterranean.

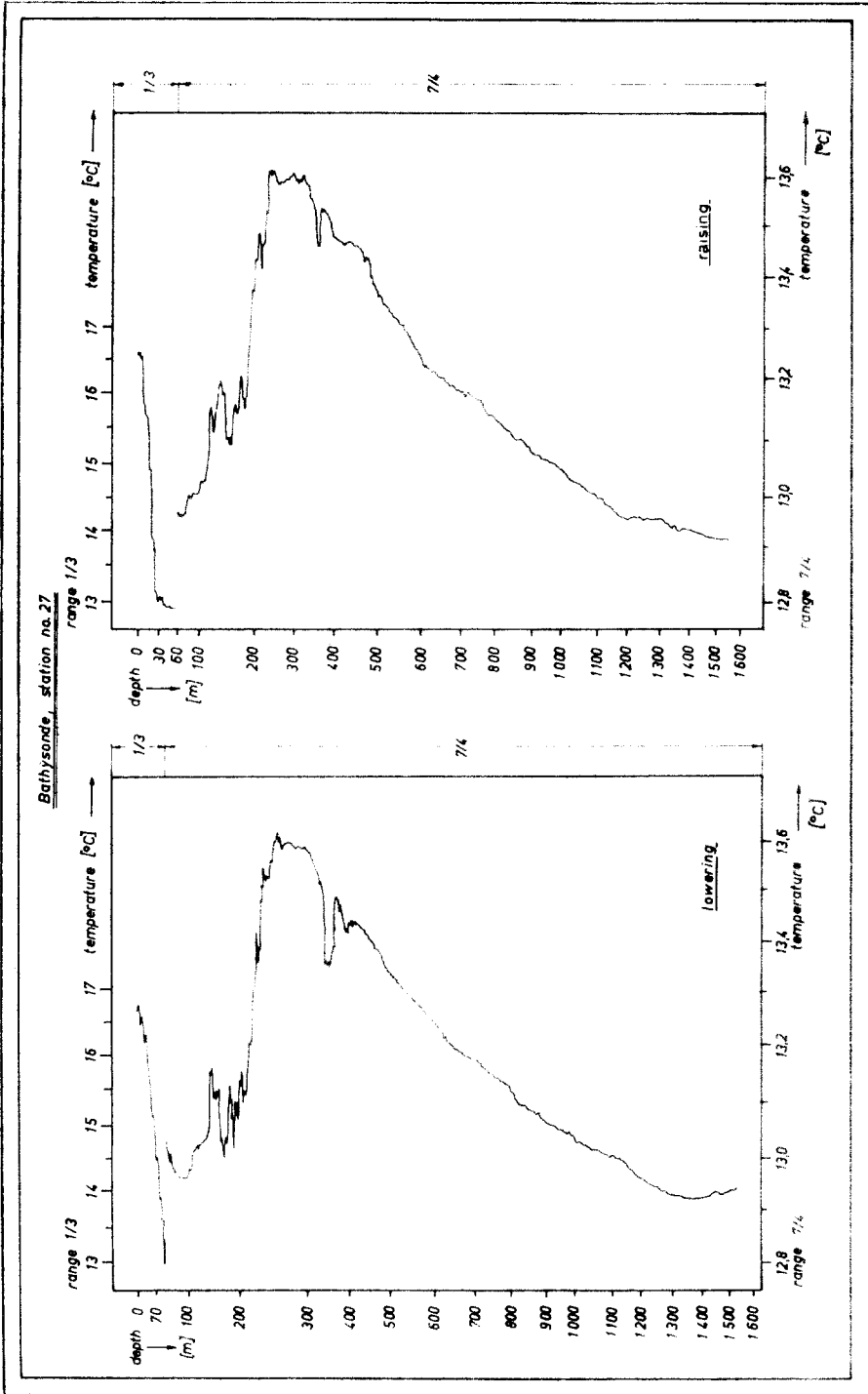


FIG. 4. Temperature record in the Mediterranean.

from that with reversing thermometers is less than  $0.02^{\circ}\text{C}$  if the calibration curve is corrected by  $0.03^{\circ}\text{C}$ . This correction is necessary because apparently the temperature measuring circuit is not yet stable enough for longer periods (i.e. months). Test series are now being carried out to show the exact value of this frequency drift to explain the causes for these deviations. Of course, the usefulness of these measurements is not limited as long as the calibration corrections are based on a number of comparative measurements.

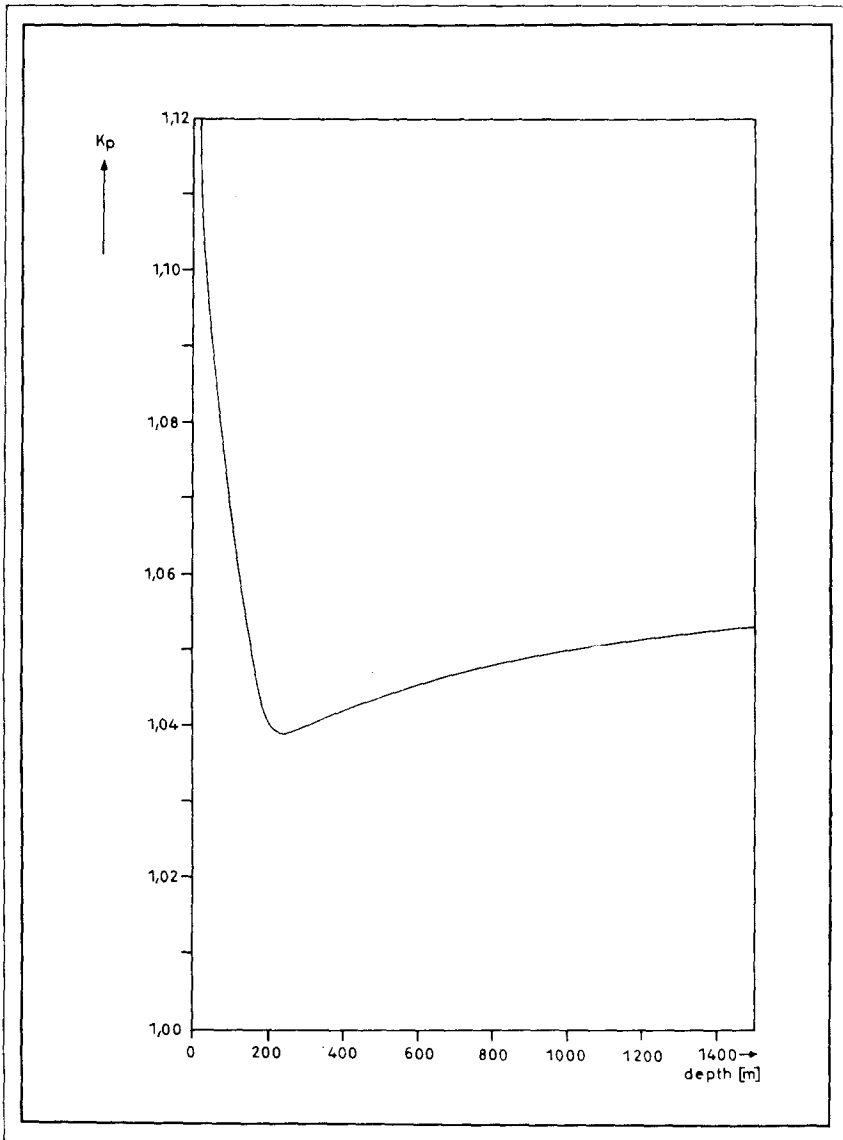


FIG. 5. Pressure dependence factor  $K_p$  of the bathysonde.

Evaluation of the conductivity records is much more difficult. It will not suffice to consider only the statements of THOMAS *et al.* (1934), and BEIN *et al.* (1935) about the dependence of the electrical conductivity on temperature and salinity, because with *in situ* measurements their dependence on

pressure must also be considered. This problem has been investigated by several others (HAMON 1958; BRADSHAW 1962; HORNE and FRYINGER, 1963), but as yet no definitive measurements have been made. Despite this a first impression of the usefulness if the *in situ* conductivity measurements can be obtained with the following formula derived from BRADSHAW's tentative results which was used as an approximation for the evaluation of the measurements carried out in the Mediterranean:

$$C_p = C_1 + 1.2 \times 10^{-4} Sp \quad (1)$$

$C_p$  is the conductivity in  $10^{-3} \Omega^{-1} \text{cm}^{-1}$  under the pressure  $p$ ;  $C_1$  is the conductivity in  $10^{-3} \Omega^{-1} \text{cm}^{-1}$  under the pressure 1 atm, calculated from the data of THOMAS, THOMPSON and UTTERBACK (1934);  $S$  is the salinity in ‰;  $p$  is the pressure in  $\text{kg/cm}^2$ . As the conductivity probe also proved to be dependent on pressure the following formula was finally used:

$$C_r = K_p \cdot C_p \quad (2)$$

$C_r$  is the recorded conductivity;  $K_p$  is the factor which indicates the pressure dependence of the probe itself. One thus obtains:

$$C_r = K_p (C_1 + 1.2 \times 10^{-4} Sp) \quad (3)$$

$K_p$  was determined using all available measurements (FIG. 5). FIG. 6 represents the recorded conductivity  $C_r$  (in simplified form, see FIG. 3), of the conductivity  $C_1$ —calculated for the measuring points of the Nansen-bottles and of the corrected conductivity  $C_{1k}$ , calculated from equation (3):

$$C_{1k} = \frac{C_r}{K_p} - 1.2 \times 10^{-4} Sp \quad (4)$$

It is possible to correct the recorded conductivity and to use it together with the temperature as a basis for the calculation of density. However, the same accuracy of  $0.02 \cdot 10^{-3} \Omega^{-1} \text{cm}^{-1}$  observed for atmospheric pressure cannot yet be obtained for *in situ* measurements as  $K_p$  is not yet exactly known. Since the measurements described above were made, the manufacturers of the bathysonde have begun tests, aimed at reducing the influence of the factor  $K_p$  by a re-design of the conductivity sonde and thus simplifying the evaluation of the conductivity recordings.\*

The present state of the technique described is that with the improvements mentioned, we can now record temperature and electrical conductivity continuously down to a depth of 2000 m within a short period. The resetability of temperature measurement is better than  $\pm 0.02^\circ\text{C}$ , that for electrical conductivity is expected to be better than  $\pm 0.02 \cdot 10^{-3} \Omega^{-1} \text{cm}^{-1}$ , and that for pressure equalling about 1 per cent of the total depth range.

A study of the measurements made up to this point indicates that the *in situ* measurements involve problems to be solved, which, on the one hand, are dependent on our knowledge of fundamental relationships in sea water, and which, on the other hand, are connected with practical difficulties in the measuring technique used. Investigations to solve these problems are under way. Measurements on the pressure dependence of conductivity are being carried out or planned at several institutions (among others, Kiel University), and the relation between density and electrical conductivity have already been investigated in Great Britain by COX, *et al.* Further technical improvement of the system used in the bathysonde will also be continued. As mentioned before, test series are being made at the moment to elucidate and to eliminate the drift of the temperature calibration. Furthermore, an attempt is being made to reduce the effect of the factor  $K_p$ .\* The increased accuracy of *in situ* measurements in the future will depend on how soon these problems can be solved.

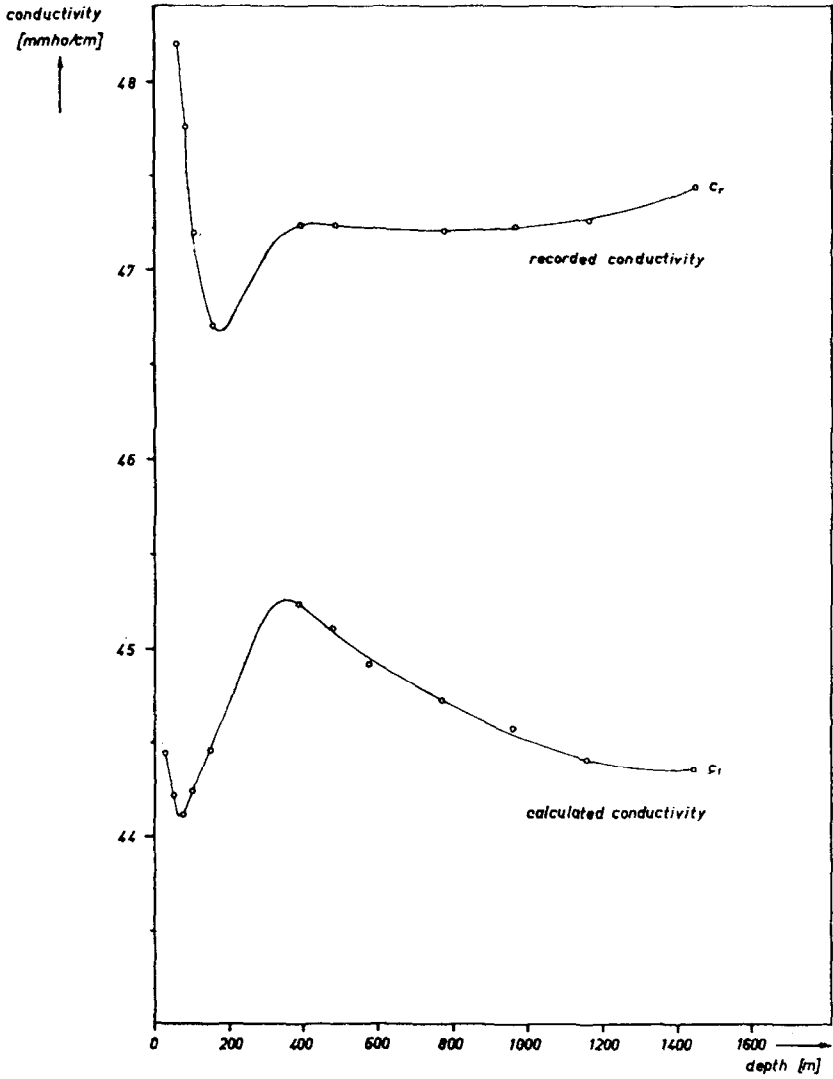
\*The first tests of the re-designed conductivity sonde carried out by KROEBEL and KRAUSE in April 1963 showed that there is almost no pressure dependence of  $K_p$  when using this new probe.

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Bathysonde, station no. 27



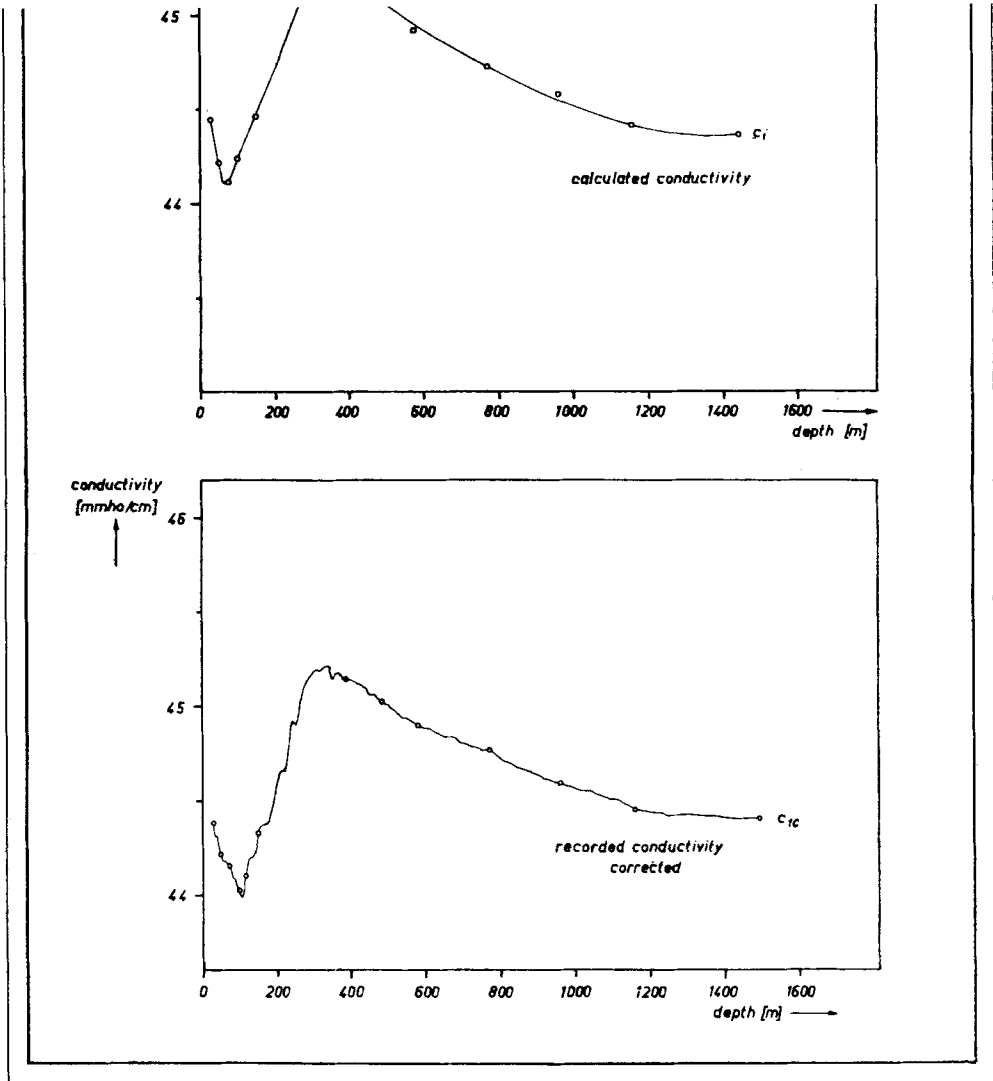


FIG. 6. Recorded conductivity  $C_r$ , calculated conductivity  $C_1$  and corrected conductivity  $C_{1c}$ .

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