

BERICHTE

**aus dem Fachbereich Geowissenschaften
der Universität Bremen**

No. 236

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REPORT AND PRELIMINARY RESULTS OF
POSEIDON CRUISE 305
LAS PALMAS (SPAIN) - LISBON (PORTUGAL)
October 28th -November 06th, 2003

Berichte, Fachbereich Geowissenschaften, Universität Bremen, No.236 ,
43 pages, Bremen 2005



ISSN 0931-0800

The „Berichte aus dem Fachbereich Geowissenschaften“ are produced at irregular intervals by the Department of Geosciences, Bremen University.

They serve for the publication of experimental works, Ph.D.-theses and scientific contributions made by members of the department.

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Citation:

Meinecke, G. Dr. and participants
Report and preliminary results of Poseidon Cruise 305, Las Palmas – Lisbon, 28.10. – 06.11.2003.
Berichte, Fachbereich Geowissenschaften, Universität Bremen, No. 236, 43 pages, Bremen, 2005

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1. Participants

Participants R/V POSEIDON cruise 305

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IFM	Institut für Meereskunde, Universität Kiel, Düsternbrooker Weg 20, 24105 Kiel, Germany
ULPGC	Universidad de Las Palmas de G. Canaria, Edificio de Ciencias Básicas, Campus Universitario Tafira, E-35017 Las Palmas de Gran Canaria, Canary Islands, Spain

2. Research Objectives

The upwelling area off NW-Africa is one of the most important upwelling systems of the global ocean, influenced by high amounts of Sahara dust which is transporting nutrients into the ocean. Both factors are of fundamental importance for the particle production in the ocean, influencing the processes of the biological carbon pump system. Hence, they are controlling factors of the global atmospheric CO₂-budget. Despite the main driving-force for climatic variability is located in the North-Atlantic, the upwelling area off NW-Africa is suitable to reconstruct the past climatic variability, via observation of present in-situ environmental datasets. During R/V POSEIDON cruise 305 it was planned to work in the main research area Canary Islands.

DOLAN (*Operational Data Transmission in the Ocean and Lateral Acoustic Network in the Deep-Sea*)

The second main topic of R/V POSEIDON cruise 305 will be the work at DOLAN site. The station is located 25 nm west of ESTOC site and comprises technological devices for transmission of scientific data sets by means of acoustic communication in the water column via satellite into the internet and research institutes.

DOBS (*Deep Ocean Bottom Station*)

This mooring array is linked to the DOLAN surface buoy mooring (SBU) as an additional acoustic client and will be maintained during this cruise.

ANIMATE (*Atlantic Network of Interdisciplinary Moorings and Time series for Europe*)

Finally, the third task in this research area will concentrate on the ANIMATE EU project, which is closely linked to the ESTOC and DOLAN project. In the ANIMATE project, moorings were deployed on key sites in the northern Atlantic (ESTOC, Canary Islands; PAP, Porcupine Abyssal Plain; CIS, Central Irminger Sea) in order to gain data of CO₂, nutrients and fluorescence, which will be transmitted directly via satellites to the participating scientific institutes. A significant element in ANIMATE is the technology for the transmission of datasets from deep-sea, still in use in the DOLAN project. Till year 2003, ESTOC was used as reference site for the subtropical NE-Atlantic within the ANIMATE project. Since spring 2003, a mooring array (ANIMATE Canary Island, ACI), consisting of several scientific sensors (MicroCats, currentmeter, ADCP) was moored 25 nm northwest of ESTOC.

3. Narrative of the Cruise

R/V POSEIDON left the port of Las Palmas on October 28th with heading to ANIMATE position. During the transit 6 XBT's were launched. In the afternoon at the same day station work at ANIMATE site started with two CTD/Rosette casts down to 3610 m water depth. In the morning of October 29th the ANIMATE ACI-2 mooring was successful recovered and R/V POSEIDON steamed on to DOLAN position. After arriving at the DOLAN position the SBU surface buoy was recovered until afternoon. Subsequently several acoustic tests were done. In the beginning of October 30th the first scientific task was the lowering of two CTD/Rosette cast down to 3609 m water depth. As preparation work for the new ANIMATE mooring work was continued with a CTD/MicroCats calibration cast down to 500 m water depth using the rosette frame. In addition, one NOAA drifter was deployed. In the afternoon some transducer tests were done.

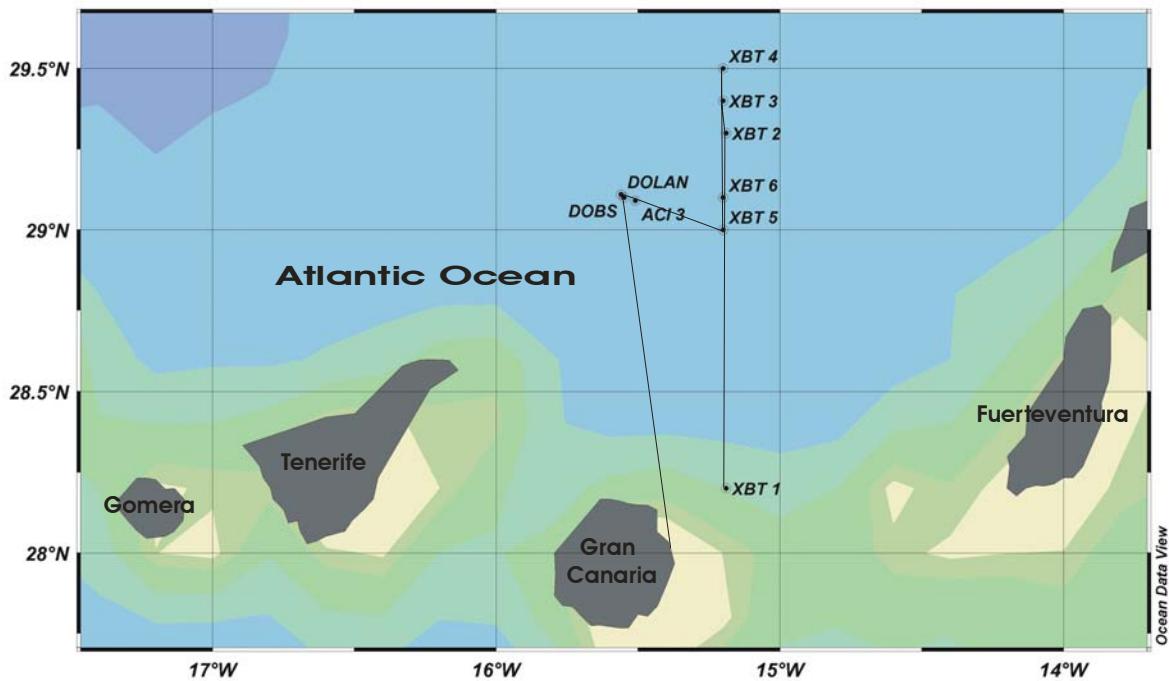


Figure 1: Cruise track and main stations during R/V POSEIDON cruise 305.

October 31st started with several acoustic tests. After that, the DOLAN-SBU was redeployed. The noon was used for communication tests. The scientific work at this day finished with acoustic tests and R/V POSEIDON left DOLAN site with heading to ANIMATE position. The next day the ANIMATE ACI-3 and the new DOBS mooring array were successfully deployed. During the forenoon of November 2nd two CTD/Rosette cast down to 3613 m were lowered. In the afternoon station work was continued with operation of another two CTD/Rosette casts down to 3610 m water depth. The scientific work ended with several modem tests and was finished in the early evening. The R/V POSEIDON steamed back to the Canaries and arrived at Las Palmas harbour late in the evening. All station work could be completed as planned.

4. Scientific Report

4.1 Particle Sampling with Sediment Traps

The particulate material collected will be analysed to determine total flux, particulate flux, particulate organic carbon, particulate nitrogen, biogenic opal, carbonate and stable isotopes of organic matter, and lithogenic material. The trapped material also will be investigated for species composition of the planktonic organisms (pteropods, foraminifera, coccolithophorides and diatoms). The objective of these studies is to identify signals of seasonal variations in those components, which play an important role in the sediment formation process. The results of these investigations will form a basis for the reconstruction of paleo-current and paleoproduction systems of the Canary Island region.

All data of recovery and deployment of the mooring arrays are listed in Tab. 1, together with sampling data of sediment traps.

4.1.1 ANIMATE Canary Island Mooring (ACI-2/ACI-3)

On October 29th the ACI-2 mooring, located at 29°08,00'N and 15°50,00'W in 3628 m water depth, was recovered. This study site was at least deployed in spring 2003 during the R/V POSEIDON cruise 296. Attached to the ACI-2 array were one sediment trap and one currentmeter (other devices described in chapter 4.2). The sediment trap provided the whole sample set of 14 cups. The array was redeployed as ACI-3 with the same configuration on October 31st. It is planned to recover this mooring array in spring 2004 with R/V POSEIDON.



Figure 2: Recovered SN 532 McLane sediment trap.

Table 1: Mooring data for recoveries and redeployments during R/V POSEIDON cruise 305.

Mooring	Position	Water depth (m)	Interval	Instr.	Device (m)	Intervals depth (no x days)
---------	----------	--------------------	----------	--------	---------------	--------------------------------

Mooring recoveries

ANIMATE ACI-2	29°09,60'N 15°50,05'W	3628	20.04.03 - 04.04.04	SN 532 (SOC) RCM 8	2996 3019	2 x 21, 11 x 28
------------------	--------------------------	------	------------------------	--------------------------	--------------	-----------------

Mooring deployments

ANIMATE ACI-3	29°09,60'N 15°50,05'W	3628	16.11.03 - 20.06.04	SN 532 (SOC) RCM 8	2996 3019	5 x 21, 8 x 14
------------------	--------------------------	------	------------------------	--------------------------	--------------	----------------

Instruments used:

SN 532
RCM 8= SOC McLane
= Aanderaa current meter, RCM 8

4.2 Equipment Development and Tests

4.2.1 DOLAN-SBU and DOBS-N

During R/V POSEIDON cruise 305 the DOLAN mooring was recovered for maintenance reasons and for integration of additional components into the Surface Buoy Unit (SBU). The SBU operates since 1997 and was formerly part of the DOMEST project. The unit serves for the development of satellite based telemetry technologies including data transmission into and from the deep ocean via acoustic modems. The data link is based on a sensor network moored in the Canary Island area.



Figure 3: Recovery of the DOLAN SBU.

On October 29th the DOLAN mooring array was recovered, which is located at 29°11,03'N and 15°55,36'W at a water depth of 3630 m. The last routine maintenance has been carried out during cruise M 58/3 in spring 2003. Fig. 4 shows the slide bio fouling of the SAMI sensor.

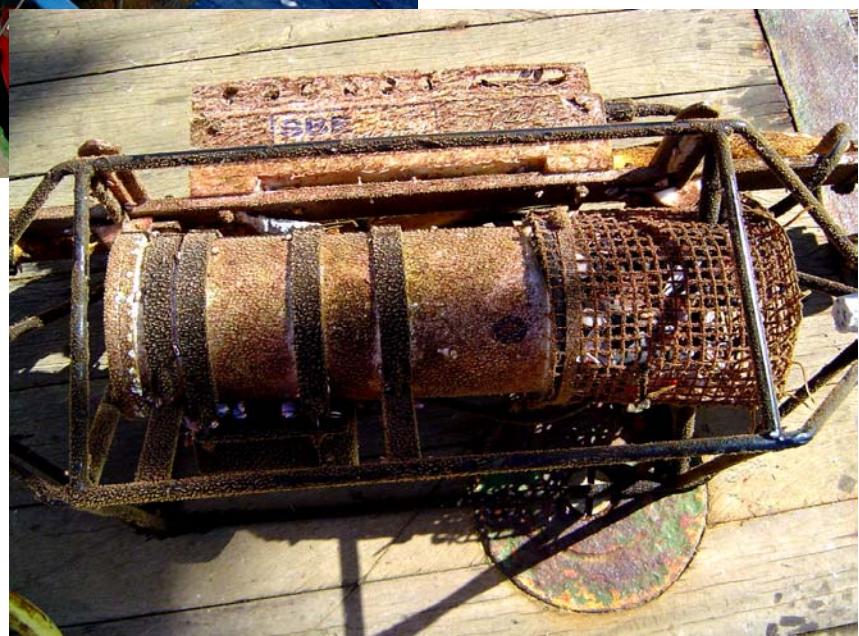


Figure 4: Bio fouling of the SAMI sensor and the MicroCat.

Configuration of the SBU

The configuration of the surface unit has not changed compared to the earlier deployment. All sensors have been maintained, the wind vane and the anemometer have been repaired.

The Inmarsat Mini-C tracking unit has been checked in order to determine the high power consumption during the last deployment phase. The measurement shows a low consumption, but the batteries were empty again after two weeks deployment, due to a cable problem.

Configuration of the DOLAN buoy after POS305

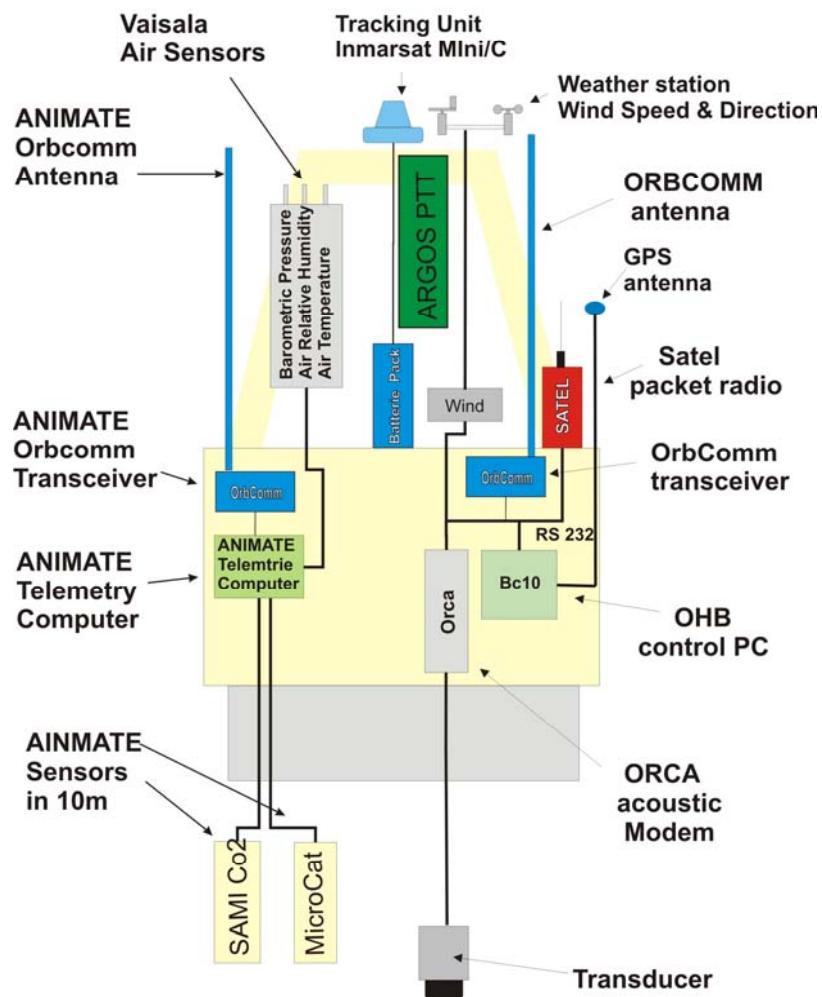


Figure 5: Configuration of the DOLAN buoy after R/V POSEIDON cruise 305.

The ANIMATE telemetry for the SAMI CO₂ sensor and the MicroCat at 10 m water depth has been working well, also the set of Vaisala air sensors with air temperature, humidity and barometric pressure. The telemetry has been maintained and redeployed.

The main work was on the underwater acoustic link. A number of tests have been performed with the SBU and the DOBS-N unit. A new microcontroller board has been

developed in order to implement new sensors and an automatic scheduled reporting of sensor data. An echo-functionality has been implemented for test purposes. These features have been tested with the underwater unit and surface unit. It turned out that the BC10 computer was not able to conduct the messages generated on the DOBS-N sensor frame. The functionality was in the software documentation, but did not work.

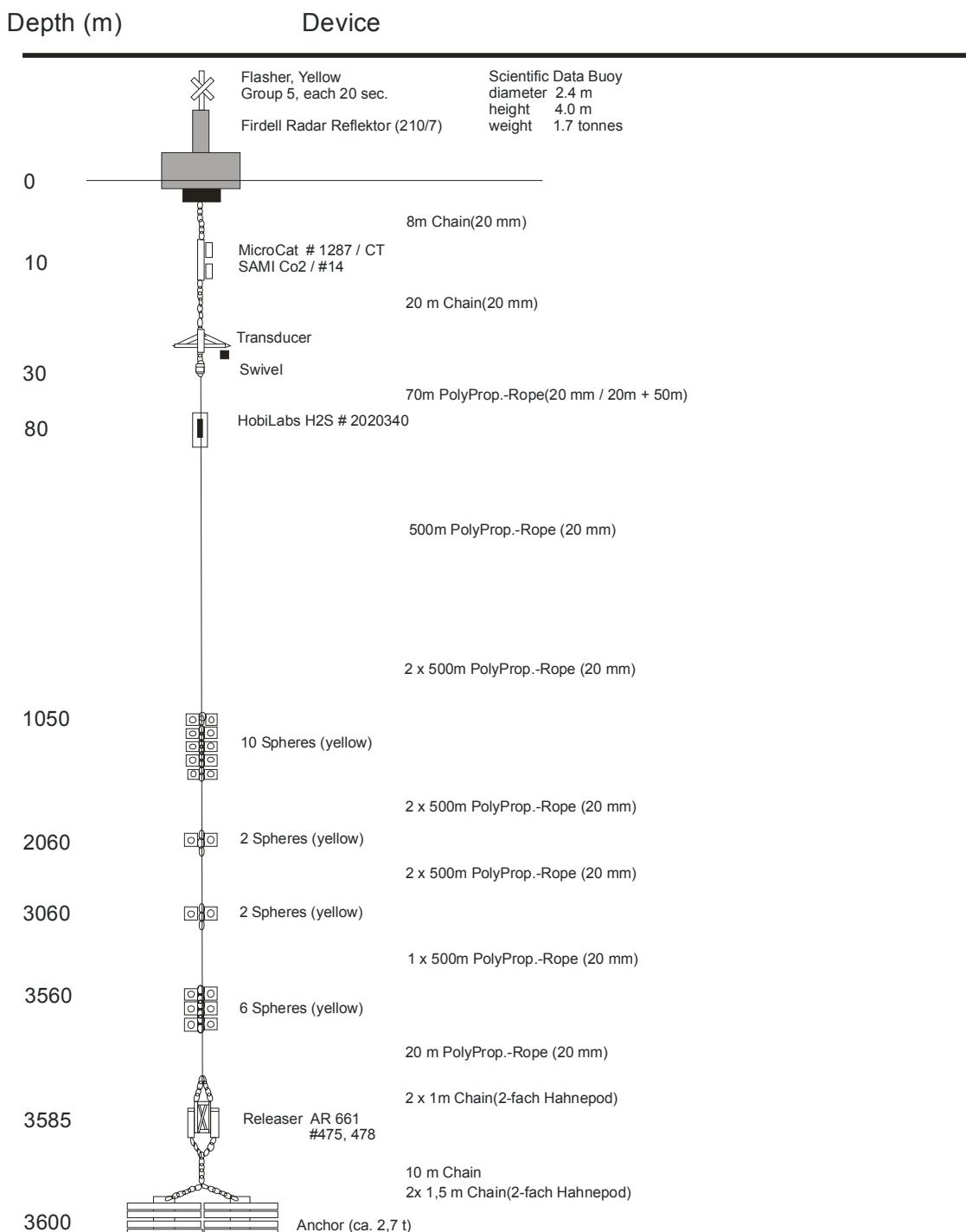


The DOLAN-SBU mooring array was redeployed on October 31st. The next routine maintenance is planned for the POSEIDON cruise 310 in spring 2004.

Figure 6: Redeployment of the DOLAN-SBU.



Figure 7: Deployment of the SAMI sensor, MicroCat and the transducer.



Mooring: DOLAN SBU (Surface Buoy)

Cruise: POS 305

Area: Canary Islands, 60 nm north of Gran Canaria

Water depth: ca. 3630 m

Deployment date: 31.10.2003

Lat 29°11.33' N
Long 015°54,9' W

Figure 8: Drawing of the DOLAN SBU mooring.

During POSEIDON cruise 305 a new mooring was setted. The DOBS-N array is closely linked to the DOLAN site, and was deployed on November 1st. It contains additional sensors, like a scattering sensor, and acoustic client units.

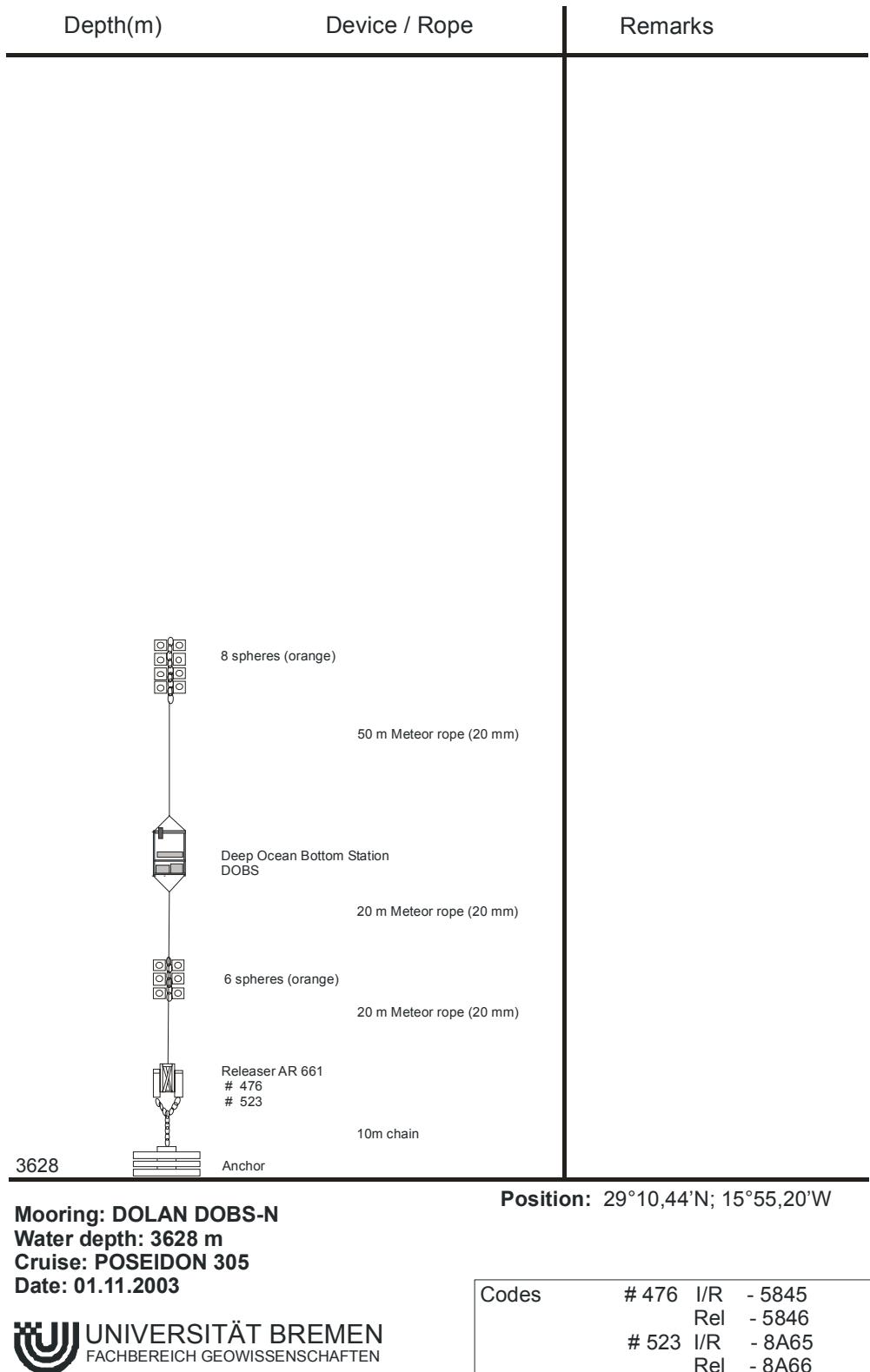


Figure 9: Drawing of the DOBS-N mooring.

4.2.2 SAMI (CO₂ sensor)

The SAMI-CO₂ is a renewable reagent fibre optic sensor for measuring the partial pressure of carbon dioxide in water. It is capable of measuring the partial pressure of carbon dioxide over a range of approximately 200-600 μatm with a precision of $\sim 1 \mu\text{atm}$, unattended for up to one year. Its PVC housing is rated to withstand pressures up to 100 m. The sensor had been deployed for the second time within the DOLAN array at a depth of 10 m, recording data in two hour intervals. The recorded data of the SAMI-CO₂ sensor were not read out after recovery and the sensor was sent back to the manufacturer, via IfM, for maintenance. On October 31st a new SAMI-CO₂ was deployed at a depth of 10 m within the DOLAN array, after an onboard testing phase.

4.2.3 Fluorometer

The HydroScat-2 is a fully autonomous in-situ optical backscattering sensor that measures the backscattering coefficient at two wavelengths and fluorescence at one wavelength. Measurements are made once per hour providing an accurate description of the particles in the water column and the chlorophyll concentration. The sensor had been deployed for the second time within the DOLAN array at a depth of 80 m recording data in 60 min intervals. The recorded data of the Fluorometer were read out after recovery. The Fluorometer was calibrated on October 31st and redeployed on the same day.

4.2.4 Nutrient Analyser

The NAS-2E is an in-situ nutrient analyzer for high-frequency time-series determination of nutrient concentrations in marine and fresh waters. Four versions are available for the measurement of nitrate (and/or nitrite), phosphate, silicate and now ammonia. The NAS-2E is typically deployed unattended for periods up to 60 days, although much longer deployments have been achieved. The device may be used near surface, in buoy and riverine applications, or be deployed at depths to 250 m in taut-line mooring scenarios. On the ANIMATE moorings only Nitrate was measured in the first instance. The data were read out, but due to several problems, which could not solve onboard, the Nutrient Analyzer was not redeployed.

4.2.5 MicroCats

The MicroCats are high accuracy temperature and conductivity sensors which record and internally store these two variables at high data rate (e.g. every 10 min) for up to one year. Within the ACI array the MicroCats are deployed in sets of single sensors, moored at specific depths to follow mixed-layered evolution and processes. The data are recorded in the internal memory of the MicroCats and transmitted to the ARGOS telemetry via an inductive link. The ARGOS telemetry sends the data online via satellite link.

During the cruise the MicroCats have not been read out, only calibrated prior to redeployment. The MicroCats of the ACI array have been rearranged according their mooring depths.

4.2.6 ANIMATE

The ANIMATE array was at least deployed during POSEIDON cruise 296 on April 12th. The ACI-2 was recovered on October 29th. It includes the ARGOS telemetry buoy, 8 MicroCats, a floatation sphere with an ADCP, one sediment trap and one currentmeter. The array was redeployed as ACI-3 on November 1st with the same configuration as ACI-2.



Figure 10: Deployment of the floatation sphere telemetry.



Figure 11: Deployment of the ARGOS telemetry.

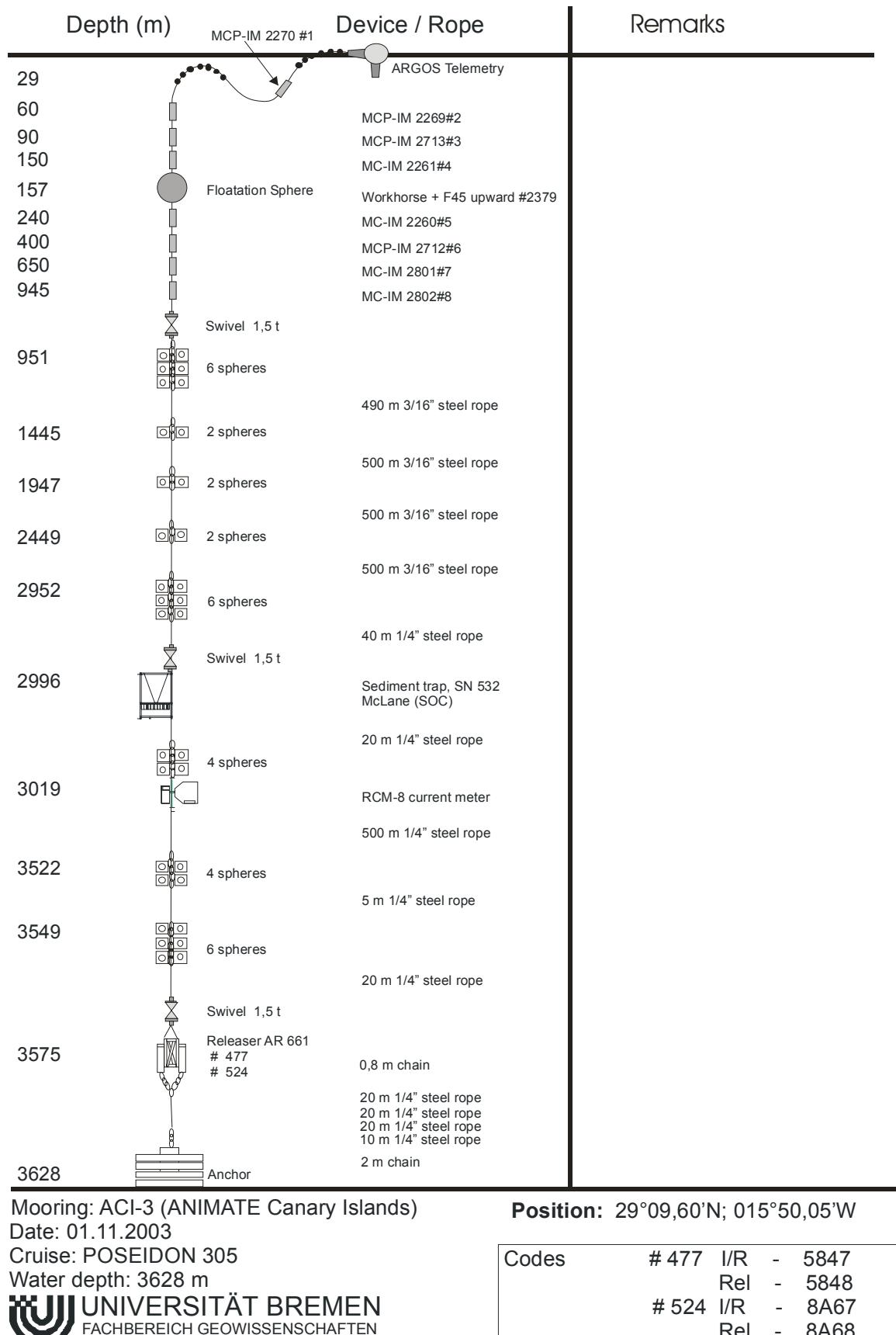


Figure 12: Drawing of the ANIMATE mooring array ACI-3.

4.2.7 Acoustic Modem

Another scientific task of the POSEIDON cruise 305 was the test of a new underwater acoustic modem. The test has been carried out on November 2nd at the DOLAN position (29°11,04'N, 15°55,44'W). It included the installation off the components, a test on deck, one test profile down to 2500 m water depth and the deinstallation off the components. The underwater unit was attached in a frame, which was placed at a disposal by the University Bremen. The deck unit could smooth connected to the onboard LAN net. Although the sender was working, the onboard test phase failed. We decided to run the test profile without a successful air test. During the profile it was tried to establish an acoustic communication in several water depths (Tab. 2).

downwards	communication	upwards	communication
100 m	✓	2500 m	-
500 m	✓	2300 m	-
1000 m	✓	2200 m	-
1500 m	✓	2100 m	-
2000 m	✓	2000 m	-
2500 m	-	1800 m	-
		1000 m	-
		200 m	-

Table 2: Water depth of the communication profile.

Indeed often more than one attempt was necessary to build up a communication, but at least in all depths of the downwards profile the communication could hold on. At a depth of 2500 m it was impossible to establish a contact, despite of several attempts. During the upwards profile it was not possible to get any connection. After the test run the different components were controlled and the batteries were reloaded. The rechargeable battery of the underwater unit was viewable discharged, while the batteries of the deck unit were nearly full.

4.2.6.1 Evaluation

The test shows, that the modem is principally able to send data up from 2000 m water depth. In most of the water depth several attempts were necessary to get a stable communication. This problem could be caused by the ships background noise, and it is well known from other acoustic modems. To eliminate this noise, it seems to be useful to test the modem on a buoy. What although should be tested is the effective data transmission rate and the failure rate. Both could not be tested during this cruise, due to missing parameters.

Condensed, the device has the status of an advanced prototype. Several points have to be worked on, before going in series production:

- integration of an user interface
- extend the working depth
- energy consumption (sleep / wake up mechanism)

4.3 Marine chemistry

During R/V POSEIDON cruise 296 the biogeochemical monthly samplings at the ESTOC station (European Station for Time series in the Ocean Canary Islands), which were continuously done since 1994, were made.

Calibration casts with CTD/Rosette were also made to accomplish the requirements of the sensors being recovered and deployed.

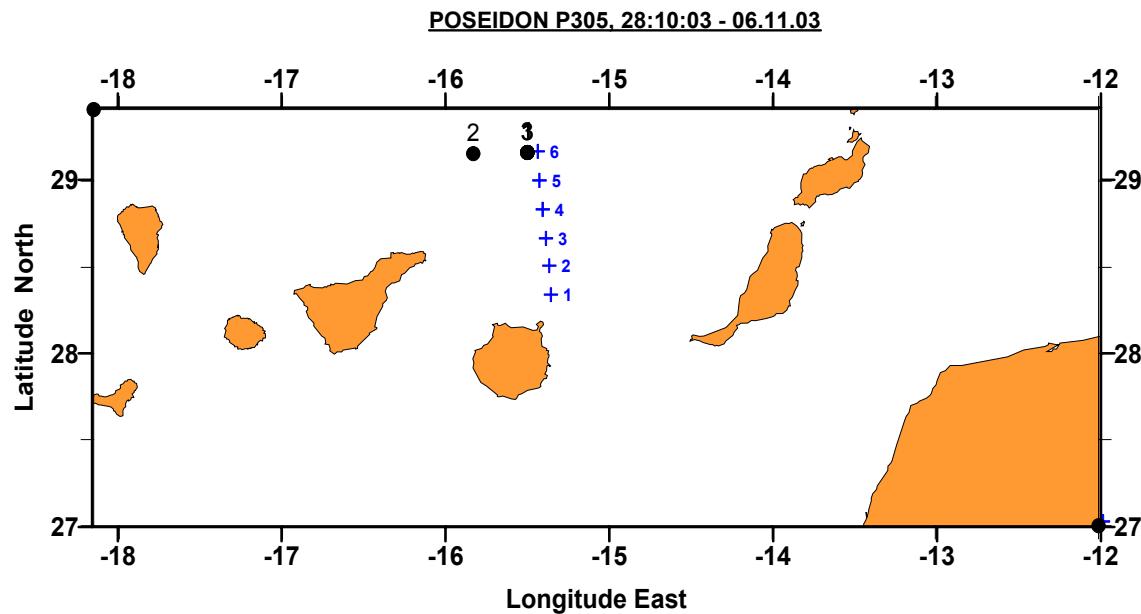


Figure 13: Position of the CTD stations (dots) and XBT launches (crosses) made by ICCM along R/V POSEIDON cruise 305.

Three stations with several casts were sampled at the ESTOC and the DOLAN positions (see map in Fig. 13). The two samplings at ESTOC were run to the bottom and the calibration cast for the fluorometer was only made to 500 m of nominal depth due to restrictions of the device. A CTD/Rosette unit with 12 bottles was used. Physical (CTD, salinity) and biochemical (oxygen, alkalinity, pH, nutrients, chlorophyll) parameters were measured in order to characterize the water masses present in the study area (Tab. 3). Some of the parameters (oxygen, alkalinity, pH, chlorophyll filtration) were analysed onboard after sampling and others were taken frozen to the ICCM (nutrients and filters from chlorophyll). Additionally, and as part of the ESTOC customary sampling scheme, 6 XBT's (eXpendable BatiThermograph) were launched to 1800 m on the transit from Las Palmas to the ESTOC station (Tab. 4).

Table 3: List stations sampled along the cruise between Las Palmas and ESTOC-ANIMATE (O=oxygen, A= alkalinity, P=pH, N=nutrients, S=salinity, C=chlorophyll "a", INCID.= incidences).

Date	St. #, Cast #	water depth	Lat. (N)	Long. (W)	sample depth	O	A	P	N	S	C	PARAMETERS INCID.
28.10 1, 001 3602 29°10.00' 15°30.00'												
28.10	1, 002	3602	29°10.00'	15°30.00'	2000	✓	✓	✓	✓	✓		Test cast at ESTOC station
					1800	✓	✓	✓	✓	✓		
					1499	✓	✓	✓	✓	✓		
					1300	✓	✓	✓	✓	✓		
					1200	✓	✓	✓	✓	✓		
					1100	✓	✓	✓	✓	✓		
					1000	✓	✓	✓	✓	✓		
					800	✓	✓	✓	✓	✓		
					600	✓	✓	✓	✓	✓		
					400	✓	✓	✓	✓	✓		
					299	✓	✓	✓	✓	✓		
					200	✓	✓	✓	✓	✓		
30.10 1, 003 3602 29°10.00' 15°30.00'												
					203	✓	✓	✓	✓	✓		
					152	✓	✓	✓	✓	✓		
					128	✓	✓	✓	✓	✓		
					101	✓	✓	✓	✓	✓		
					76	✓	✓	✓	✓	✓		
					51	✓	✓	✓	✓	✓		
					25	✓	✓	✓	✓	✓		Water losses
					12							
30.10 1, 004 3602 29°10.00' 15°30.00'												
					3562	✓	✓	✓	✓	✓		
					3000	✓	✓	✓	✓	✓		
					2800	✓	✓	✓	✓	✓		
					2500	✓	✓	✓	✓	✓		
					2000	✓	✓	✓	✓	✓		
30.10 2, 001 3602 29°09.61 15°49.90												
					501						✓	N
					149						✓	U
					123						✓	T
					100						✓	R
					90						✓	I
					80						✓	E
					70						✓	N
					54						✓	T
					39						✓	S
					25						✓	O
					10						✓	C
02.11 3, 001 3602 29°10.00' 15°30.00'												
					3562	✓	✓	✓	✓	✓		
					3000	✓	✓	✓	✓	✓		
					2800	✓	✓	✓	✓	✓		
					2500	✓	✓	✓	✓	✓		
					2000	✓	✓	✓	✓	✓		
					1800	✓	✓	✓	✓	✓		
					1500	✓	✓	✓	✓	✓		
					1300	✓	✓	✓	✓	✓		
					1200	✓	✓	✓	✓	✓		
					1100	✓	✓	✓	✓	✓		
					1000	✓	✓	✓	✓	✓		
					800	✓	✓	✓	✓	✓		
					800	✓	✓	✓	✓	✓		
					600	✓	✓	✓	✓	✓		
					400	✓	✓	✓	✓	✓		Water losses
					300	✓	✓	✓	✓	✓		
					200	✓	✓	✓	✓	✓		
					150	✓	✓	✓	✓	✓		
					125	✓	✓	✓	✓	✓		
					100	✓	✓	✓	✓	✓		
					50	✓	✓	✓	✓	✓		
					10	✓	✓	✓	✓	✓		

Table 4: List of XBT that were launched between Las Palmas and ESTOC during R/V POSEIDON cruise 305.

XBT sta #	Date	Latitude	Longitude
ESTOC-D6	04.04.2003	28°20,00'N	15°30,00'W
ESTOC-D5	04.04.2003	28°30,00'N	15°30,00'W
ESTOC-D4	04.04.2003	28°40,00'N	15°30,00'W
ESTOC-D3	04.04.2003	28°50,00'N	15°30,00'W
ESTOC-D2	04.04.2003	29°00,00'N	15°30,00'W
ESTOC-D1	04.04.2003	29°10,00'N	15°30,00'W

4.3.1 Water Sampling and Analysis

Samples were collected immediately after the Niskin bottles were on board from each depth. The sampling sequence was as follows:

Oxygen

Oxygen was taken in glass bottles of about 125 ml of volume which were previously cleaned and washed with HCl acid and fixed at once; then it was kept for at least six hours according to WOCE regulations and finally it was analysed at the laboratory onboard the ship. The samples were analysed using the method described in the WOCE Operations Manual, WHP Office Report No. 68/91; the final titration point was detected using a Metrohm 665 Dosimat Oxygen Auto-Titrator Analyser.

Nutrients

Nutrients were taken in polypropylene bottles which were previously cleaned and washed with HCl acid and completely dry. Samples were immediately frozen at -20°C, analysing them as soon as possible after arrival at the laboratory. Freezing the samples is a common practice; it does not or only in a non-significant way affects the nitrate+nitrite and the phosphate values (by a slight decrease) and is not noticeable in the silicate values (Kremling and Wenck, 1986; McDonald and McLunghlin, 1982).

Salinity samples were taken in dark glass bottles which were previously cleaned and washed with HCl acid. Then, they were kept in boxes to protect them from light till analysis on land.

The nutrients determination was performed with a segmented continuous-flow autoanalyser, a Skalar® San Plus System (ICCM).

Nitrate and Nitrite

The automated procedure for the determination of nitrate and nitrite is based on the cadmium reduction method; the sample is passed through a column containing granulated copper-cadmium to reduce the nitrate to nitrite (Wood et al., 1967), using ammonium chloride as pH controller and complexer of the cadmium cations formed (Strickland and Parsons, 1972). The optimal column preparation conditions are described by several authors (Nydale, 1976; Garside, 1993).

Phosphate

Orthophosphate concentration is understood as the concentration of reactive phosphate (Riley and Skirrow, 1975) and according to Koroleff (1983a) is a synonym of “dissolved inorganic phosphate”. The automated procedure for the determination of phosphate is based on the following reaction: ammonium molybdate and potassium antimony tartrate react in an acidic medium with diluted solution of phosphate to form an antimony-phospho-molybdate complex. This complex is reduced to an intensely blue-coloured complex, ascorbic acid. The complex is measured at 880 nm. The basic methodology for this anion determination is given by Murphy and Riley (1962); the used methodology is the one adapted by Strickland and Parsons (1972).

Silicate

The determination of the soluble silicon compounds in natural waters is based on the formation of the yellow coloured silicomolybdic acid; the sample is acidified and mixed with an ammonium molybdate solution forming molybdsilicic acid. This acid is reduced with ascorbic acid to a blue dye, which is measured at 810 nm. Oxalic acid is added to avoid phosphate interference. The used method is described in Koroleff (1983b).

Phytoplankton pigments

Pigments were measured using fluorimetric analysis, following the methodology described by Welschmeyer (1994). The determination was achieved using a fluorometer TURNER 10-AU-000.

Salinity

Samples were measured with a salinometer, model Autosal 8400a, whose measurement range was between 0.005-42 (psu), with an accuracy of ± 0.003 , according to the manufacturer. It was calibrated following the manufacturer's information and standardizing it with IAPSO Standard Seawater. Salinity values were calculated as practical salinity according to Unesco (1978, 1984).

Chlorophyll

Chlorophyll samples of one litre of water were taken. The chlorophyll samples were filtered immediately and the filters were frozen subsequently at -20°C. Their analyses take place at the ICCM laboratory in land.

Carbonate system measurements, in this case pH (at ESTOC only) and alkalinity: samples were taken in glass bottles and were fixed immediately on board. Finally, they were also analysed on board along the cruise. Additionally, fugacity of carbon dioxide in the air and in the seawater was determined using a flow system continuously along the ship track.

Carbonate system measurements

The pH_t in total scale (mol (kg-SW)^{-1}) was measured following the spectrophotometric technique of Clayton and Byrne (1993) using the m-cresol purple indicator (DOE, 1994). 0.0047 pH units were added to the pH experimental values in order to take into consideration the recommendations by Lee et al. (2000). A system similar to that described by Bellerby et al. (1995) was developed in our lab. The pH_t measurements were carried out using a Hewlett Packard Diode Array spectrophotometer in a 25°C-thermostated 1-cm flow-cell using a Peltier system. A stopped-flow protocol was used to analyse seawater previously thermostated to 25°C for a blank determination at 730, 578 and 434 nm. The flow was restarted, and the indicator injection valve switched on to inject 10 µl dye through a mixing coil (2 m). Three photometric measurements were carried out for each injection in order to remove all dye effect on the seawater pH_t measurement. Repeatedly, seawater measurements of the different Certified Reference Materials (CRM provided by Dr. Dickson, Scripps Institution of Oceanography) samples gave a standard deviation of ± 0.0015 ($n = 54$).

The total alkalinity of seawater (A_T) was determined by titration with HCl to the carbonic acid end point using two similar potentiometric systems, as described in more detail by Mintrop et al. (2000). In order to yield an ionic strength similar to open ocean seawater, the HCl solution (25 l, 0.25 M) was made from concentrated analytical grade HCl (Merck®, Darmstadt, Germany) in 0.45 M NaCl. The acid was standardised by titrating weighed amounts of Na_2CO_3 dissolved in 0.7 M NaCl solutions. The total alkalinity of seawater was evaluated from the proton balance at the alkalinity equivalence point, $\text{pH}_{\text{equiv}} = 4.5$, according to the exact definition of total alkalinity (Dickson, 1981). The performance of the titration systems was monitored by titrating different samples of certified reference material (CRM, batch 42) with known inorganic carbon and A_T values. The agreement between our data and CRM values was within $\pm 1.5 \mu\text{mol kg}^{-1}$. Total inorganic carbon (C_T) is computed from experimental values of pH_t and total alkalinity, using the carbonic acid dissociation constants of Mehrbach after Dickson and Millero (1987). This set of constants presented the best agreement between $C_T(\text{pH}, A_T)$ calculations and certified C_T values for CRM, batch 42, with a C_T residual of $\pm 3 \mu\text{mol kg}^{-1}$, $n=54$ (Millero, 1995, Lee et al., 1997).

Fugacity of carbon dioxide ($f\text{CO}_2$) in the air and in surface seawater was determined using a flow system similar to the unit designed by Wanninkhof and Thoning (1993) and developed by Frank J. Millero's group at the University of Miami. The equilibrator used is based on the design by R.F. Weiss and described by Butler et al (1988). The concentration of CO_2 in the air and in the equilibrated air sample was measured with a differential, non-dispersive, infrared gas analyser supplied by LI-COR (LI-6262 $\text{CO}_2/\text{H}_2\text{O}$ Analyser). The sample was measured wet and the signal corrected for water vapour using the water channel of the LI-COR detector. The instrument was operated in the absolute mode and gathered CO_2 concentrations directly from the instrument. The LI-COR instrument analyses the concentration of CO_2 every six seconds, then averaged these values over a 5-min interval, and recorded them. Atmospheric air was pumped at the bow of the ship and measured every hour. The system was calibrated by measuring two different standard gases with mixing ratios of 348.55 and 520.83 ppm CO_2 in the air. These calibrated standards were provided by the National Oceanographic and Atmospheric Administration and they are traceable to the World Meteorology Organisation scale. Our system has demonstrated a precision of less than 1 µatm and is accurate, relative to

standard gases, to 2 μatm . Fugacity of CO_2 in the seawater is calculated from the measured $x\text{CO}_2$ (mol fraction of CO_2 gas corrected to dry air and to the pressure of 1 atm).

All samples were taken using the procedures established in the WOCE Operations Manual, WHP Office Report WHPO 91-1/WOCE Report No.68/91.

4.3.2 Preliminary Results

The temperature/salinity diagrams made from the CTD casts (Fig. 14) done for the ESTOC station in October and November 2003 show at intermediate and deeper waters the same trends while on the surface waters slight variations are encountered. The intermediate waters seem to be in equilibrium, since not greater amounts of Mediterranean Water as compared to Antarctic Intermediate Water (AAIW) are found at around 1000 m of depth ($8-10^\circ\text{C}$).

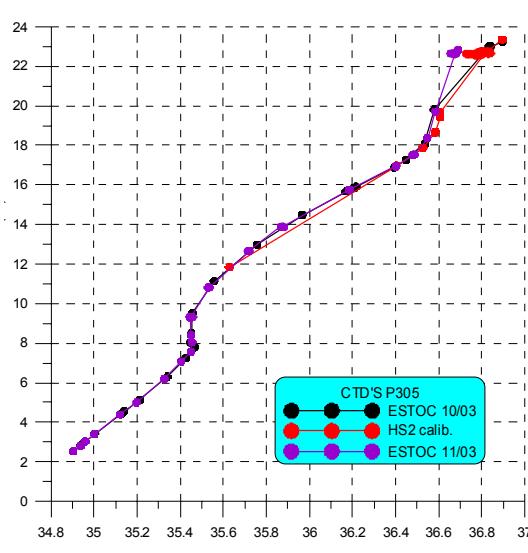


Figure 14: T/S diagrams from CTD stations of R/V POSEIDON cruise 305 at ESTOC ($29^\circ 10' \text{N}$, $15^\circ 30' \text{W}$).

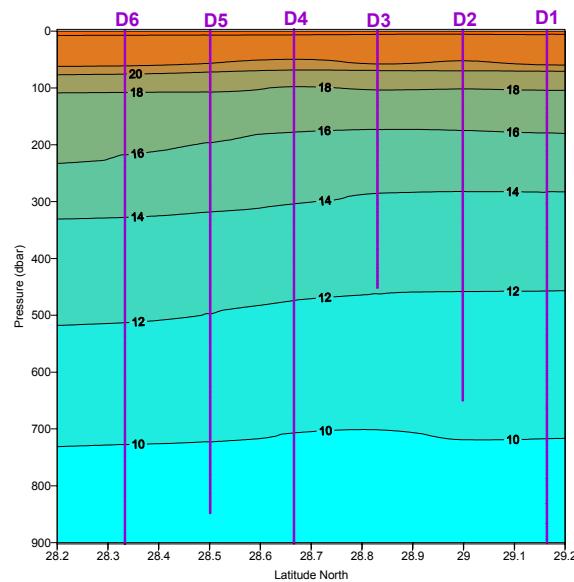
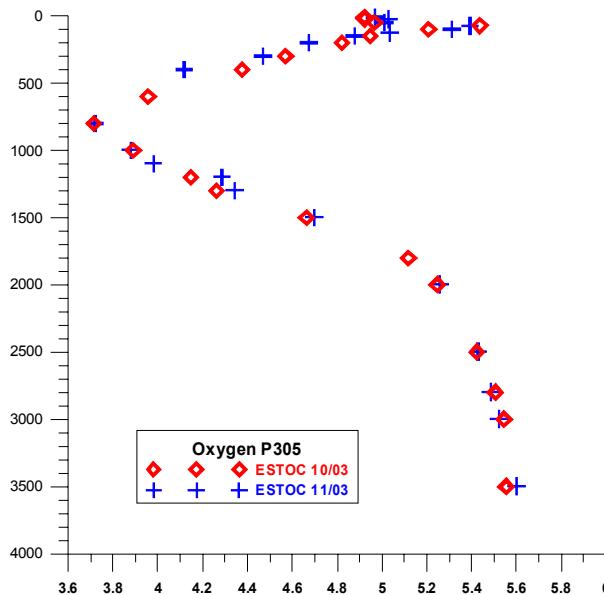


Figure 15: Evolution of the oxygen values from surface to the depth in the stations sampled during R/V POSEIDON cruise 305.

Fig. 15 shows the XBT results stating the variation of the temperature with the latitude as going north from Las Palmas harbour towards the ESTOC station, corresponding from the last XBT launch (D1) to the ESTOC site. Temperature data show a variation from 24°C at the surface to 10°C at around 700 m, having values in the water column which are normal in this area for the autumn season.



Oxygen shows as a general trend in this area of the subtropical North Atlantic with a minimum at around 800-1000 m for the ESTOC station, with values in the range of 3.6-3.8 ml/l.. With increasing depth, Oxygen shows values up to 5.6 ml/l (Fig. 16). A subsurface maximum of about the same value is also encountered.

Figure 16: Temperature variation with latitude from the 6 launches (crosses) made during R/V POSEIDON cruise 305.

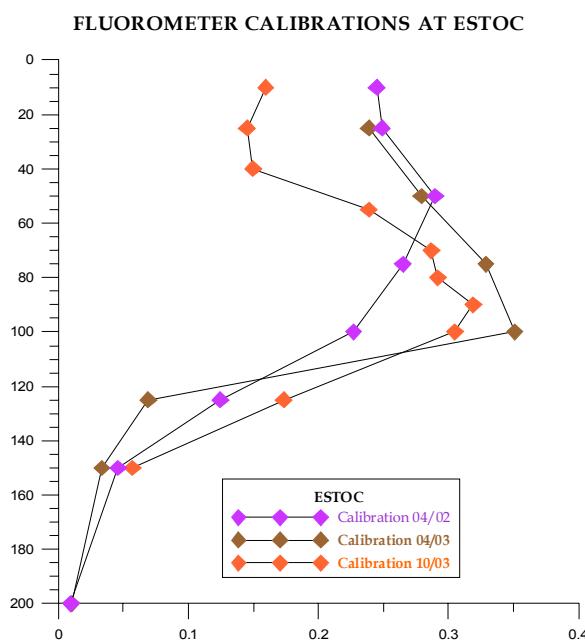


Fig. 17 shows the chlorophyll "a" profiles down to 200 m of nominal depth that were done to calibrate the ANIMATE fluorometer before each mooring deployment period at ESTOC. Values change from year to year even for the same seasonal period (compare 04/02 with 04/03 where the maximum is at different depths and shows a difference of 0.05 micrograms/l). The maximum value for the R/V POSEIDON cruise 305 calibration was found to be 0.32 micrograms/l at 100 m of depth; note that the fluorometer was moored at 90 m at ESTOC during 2003.

Figure 17: It shows the chlorophyll values to calibrate the fluorometer in previous cruises and for R/V POSEIDON cruise 305 at the ANIMATE/ESTOC mooring.

5. List of Stations

Station-No.	date 2003	Description and Devices	LAT [deg-min]	LONG [deg-min]	WD [m]	Samples	Remarks
28.10.	XBT #1		28°20,00' N	015°19,99' W	3173		
28.10.	XBT #2		29°30,00' N	015°19,98' W	3463		
28.10.	XBT #3		29°40,00' N	015°20,00' W	3584		
28.10.	XBT #4		29°50,00' N	015°20,00' W	3594		
28.10.	XBT #5		29°00,00' N	015°20,00' W	3599		
28.10.	XBT #6		29°10,00' N	015°20,00' W	3598		
28.10.	CTD/Rosette		29°09,87' N	015°30,14' W	3610	12 bottles	
28.10.	CTD/Rosette		29°10,11' N	015°30,22' W	3609	12 bottles	
29.10.	ACI-2		29°08,00' N	015°50,00' W			recovery
29.10.	DOLAN		29°10,70' N	015°56,27' W			recovery
29.10.	Acoustic test			N			
30.10.	CTD/Rosette		29°10,06' N	015°30,00' W	3609	12 bottles	
30.10.	CTD/Rosette		29°10,09' N	015°29,94' W	3609	12 bottles	
30.10.	CTD/Rosette		29°10,14' N	015°30,03' W	3608	12 bottles	
30.10.	CTD/Rosette		29°10,26' N	015°29,69' W	3608	12 bottles	
30.10.	NOAA drifter		29°10,29' N	015°29,68' W			
30.10.	CTD/Rosette		29°09,62' N	015°49,92' W	3625	12 bottles	
30.10.	CTD/Rosette		29°09,59' N	015°49,94' W	3608	12 bottles	
30.10.	transducer		29°11,05' N	015°56,32' W			
31.10.	Acoustic tests		29°10,89' N	015°55,97' W			
31.10.	DOLAN		29°11,02' N	015°56,02' W			deployment
31.10.	Communication tests		29°10,49' N	015°55,75' W			
31.10.	Acoustic tests		29°10,46' N	015°55,82' W			
01.11.	ACI-3		29°09,59' N	015°51,05' W			deployment
01.11.	DOBS-N		29°10,44' N	015°55,20' W	3629		deployment
02.11.	CTD/Rosette		29°10,01' N	015°30,06' W	3609	12 bottles	
02.11.	CTD/Rosette		29°10,22' N	015°31,17' W	3609	12 bottles	
02.11.	CTD/Rosette		29°10,00' N	015°30,00' W	3608	12 bottles	
02.11.	CTD/Rosette		29°10,05' N	015°30,11' W	3608	12 bottles	
02.11.	MODEM test		29°10,80' N	015°31,22' W	3610		

6. Acknowledgements

The scientific cruise participants would like to thank Captain Lutz Mallon and his entire crew for the good cooperation along the R/V POSEIDON cruise 305. The teamwork among the crew and the scientists during the complicated mooring work with the DOLAN data buoy and the ACI steel cable array, leads to the success of this cruise. Due to the friendly way of communication between crew and scientists, we enjoyed ones more the stay onboard the R/V POSEIDON.

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